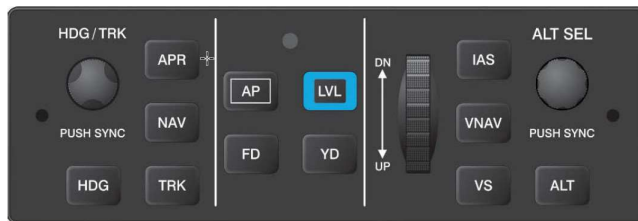


# GFC 500 Autopilot as installed in C172S N97PD (and other aircraft)

Howard Wolvinton  
2014 National CFI of the Year  
Designated Pilot Examiner  
BEFA member since 1997



GARMIN

G5 Electronic Flight Instrument  
Pilot's Guide  
for Certified Aircraft  
(includes the GFC 500)



# GFC 500 Autopilot – N97PD / RV12iS / N2365C

GMC 307 Control Unit

Digital input from ADAHRS for Roll / Pitch



G5 AI



G3X Touch



GI 275 AI



# GFC 500 Autopilot System Components



# GFC 500 Autopilot Disconnect, Trim, PPT on Yoke

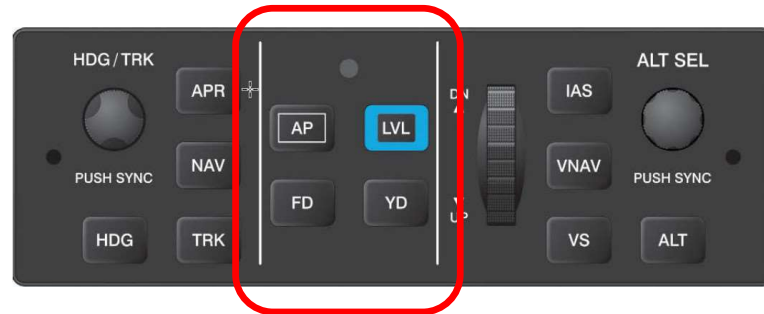
**BLACK PPT**

**RED AP Disconnect & Trim Interrupt**

**Manual electric trim**



# GFC 500 Autopilot



**Autopilot supports 3 basic modes of operation via central control buttons:**

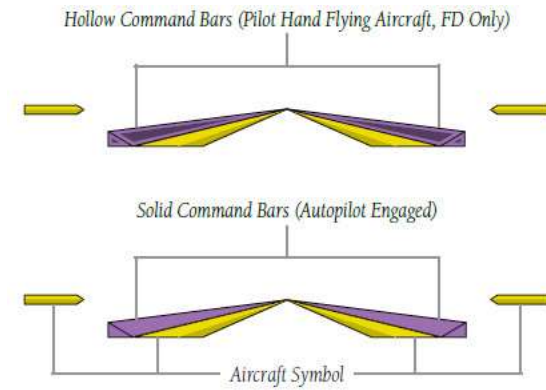
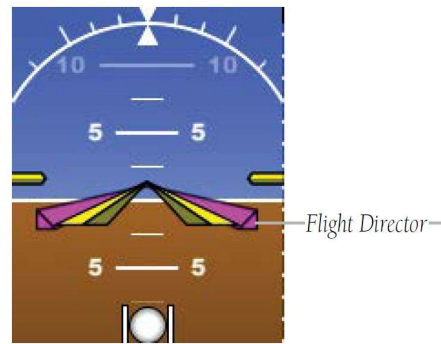
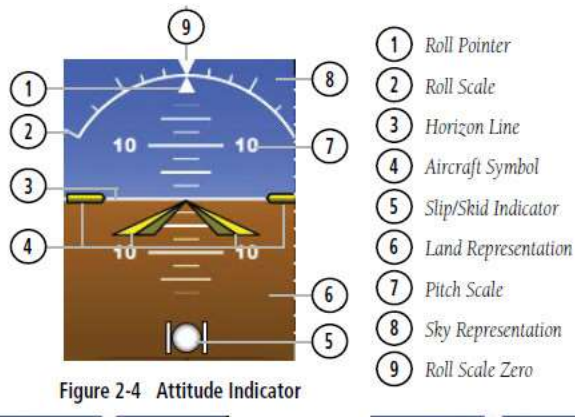
**FD** Flight Director

**AP** Full Autopilot Control

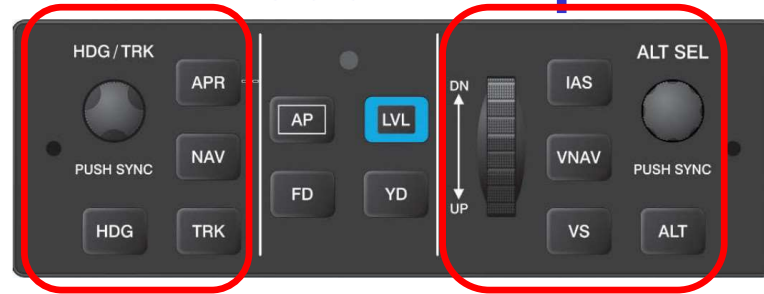
**LVL** Level Roll and Pitch

**YD** Optional Yaw Damper is not implemented

# Flight Director on G5



# GFC 500 Autopilot



**Lateral Modes (left buttons) include:**

**Heading**

**Track**

**Navigation**

**Approach (Navigation plus GS/GP)**

**Roll Hold (default no other mode)**

**Vertical Modes (right buttons) include:**

**Altitude Hold**

**Vertical Speed climb/descend (set by pitch wheel)**

**Vertical Navigation**

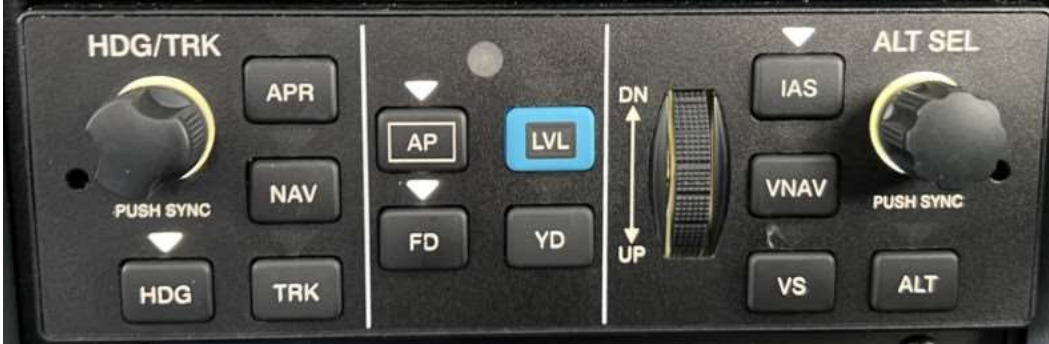
**Indicated Airspeed climb/descend (set by pitch wheel)**

**Pitch Hold (default with no other mode)**

**Pilot specified values of Heading/Track and Altitude are selected via rotary knobs on the Autopilot Mode Controller**

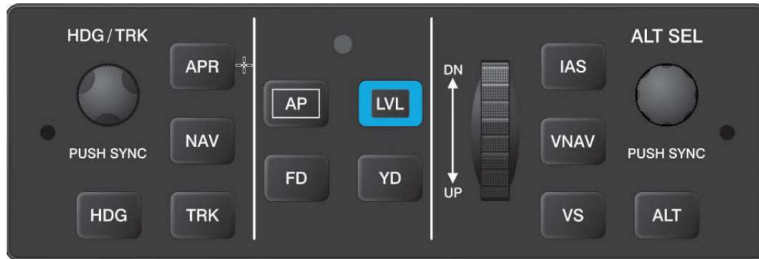
**Pressing an Active Lateral or Vertical mode causes the mode to revert to the default ROL/PIT**

# GFC 500 Autopilot



Lights over selected buttons

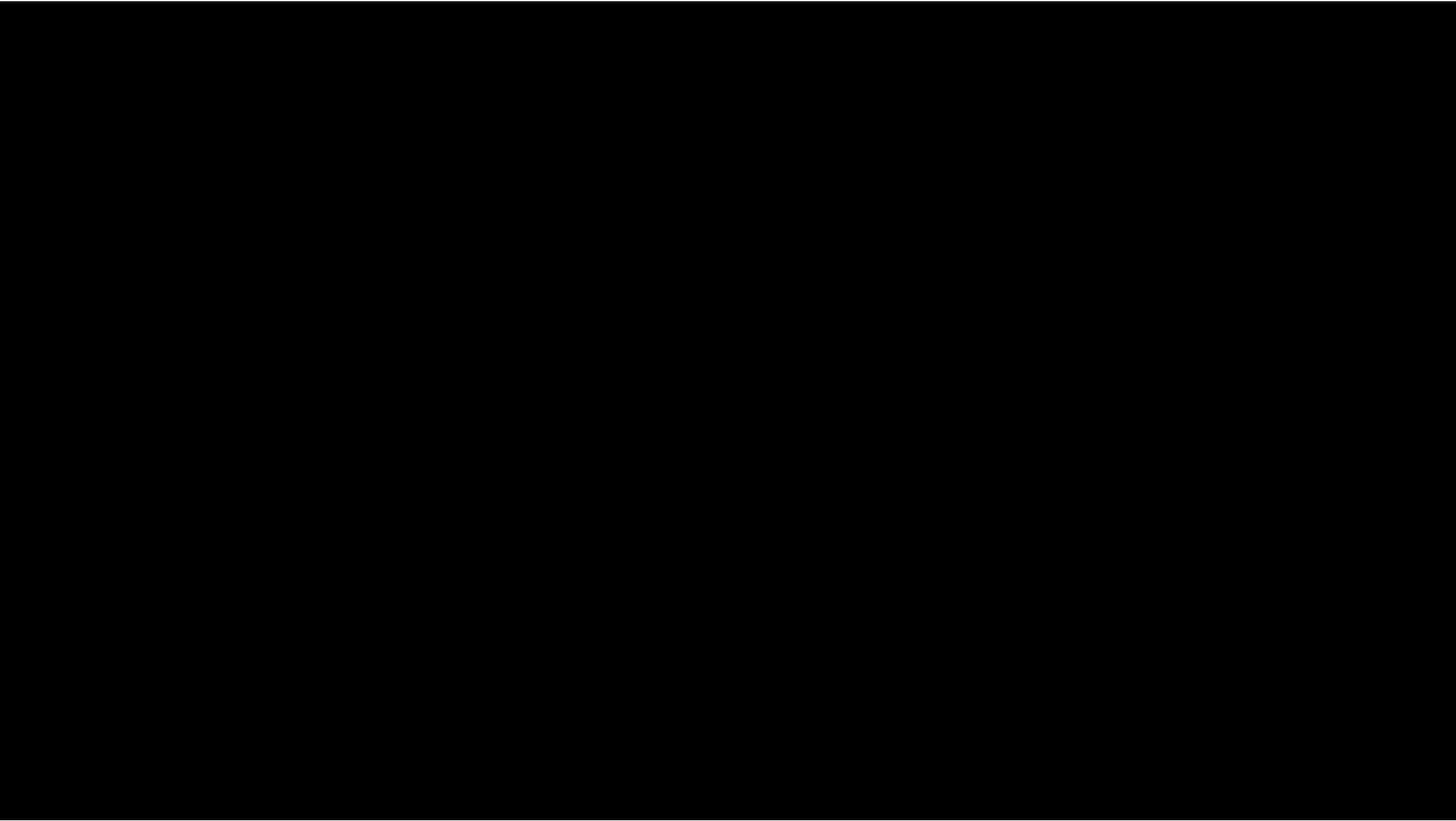
# GFC 500 Autopilot



Current autopilot modes and Armed (future) autopilot modes are displayed on the G5 AI “Score Board” [Green Active; White Armed]

A TOGA (Takeoff / Go-Around) button on the panel just above the throttle is used on the ground to select Takeoff annunciation (level wings and 7 degrees pitch up) and in the air to initiate a Go-Around, which enables a couple Missed Approach from an instrument approach





## **A Pilot's Got To Know his GFC 500 Limitations**

- 1. Pilot's Guide (G5/G3X/GI 275) must be immediately available to the flight crew**
- 2. A Pilot must be seated in the left pilot's seat, with seatbelt fastened, during all autopilot operations.**
- 3. AP use prohibited during takeoff and landing**
- 4. GFC500 AFCS preflight test must complete successfully prior to use of the autopilot, flight director or manual electric trim**
- 5. Maximum fuel imbalance with the autopilot engaged is 10 gallons**
- 6. Maximum engagement speed is 150 KIAS**
- 7. AP engagement is limited to flap positions no greater than 10°**
- 8. AP must be disengaged below 200' AGL during approach operations**
- 9. AP must be disengaged below 800' AGL for all other operations**
- 10. AP is approved for Category 1 precision approaches and non-precision approaches only**

# **GFC 500 Autopilot Test**

**An Autopilot Test is included in the runup section of the revised BEFA checklist**

- **Engage the autopilot (default Roll/Pitch mode) by the “AP” button on the control unit**
- **Ensure the AP can be overpowered (both Roll & Pitch) with the control column. The control forces will increase with AP engaged [be gentle]**
- **Note the forces required to overpower the autopilot servo clutches**
- **Verify that Autopilot disengages with the Red AP Disconnect Button**

## **GFC 500 Autopilot - Methods of Disconnect**

- **Press Red AP Disconnect Button on the Yoke (the normal method)**
- **Move the Manual Electric Trim when AP is engaged**
- **Press the AP button on the control unit when AP is engaged**
- **Pull the AP circuit breaker**

# GFC 500 Autopilot



## Typical Uses of Lateral Modes

**Heading:** fly HDG selected by pilot

**Track:** fly TRK selected by pilot

**Navigation:** track a course (GPS, VOR, LOC)

**Approach:** Navigation plus GS/GP

## Typical Uses of Vertical Modes

**Climb:** Indicated Airspeed (set by pitch wheel)

**Enroute:** Altitude Hold (following climb/descent)

**Descent:** Vertical Speed (set by pitch wheel) or

**Descent:** via Vertical Navigation

# GFC 500 Autopilot



## Typical Uses of Lateral Modes

**Heading:** fly HDG selected by pilot

**Track:** fly TRK selected by pilot

**Navigation:** track a course (GPS, VOR, LOC)

**Approach:** Navigation plus GS/GP

## Typical Uses of Vertical Modes

**Climb:** Indicated Airspeed (set by pitch wheel)

**Enroute:** Altitude Hold (following climb/descent)

**Descent:** Vertical Speed (set by pitch wheel) or

**Descent:** via Vertical Navigation

**Pitch Wheel moves nose of airplane not value**



**Note: Pilot should not move elevator with yoke while autopilot is engaged: doing so will cause the autopilot to trim in the opposite direction, potentially to full up or full down trim!**

Flying the Garmin GFC 500 Autopilot (webinar recording)



**GARMIN**  
AVIATION TRAINING

# Flight Scenario KSSF-KTFP

GFC 500 AFCS

Play (k)

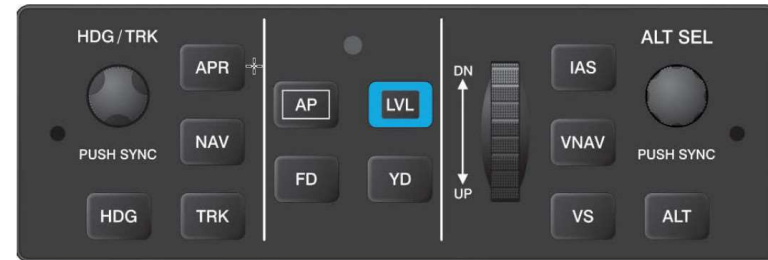
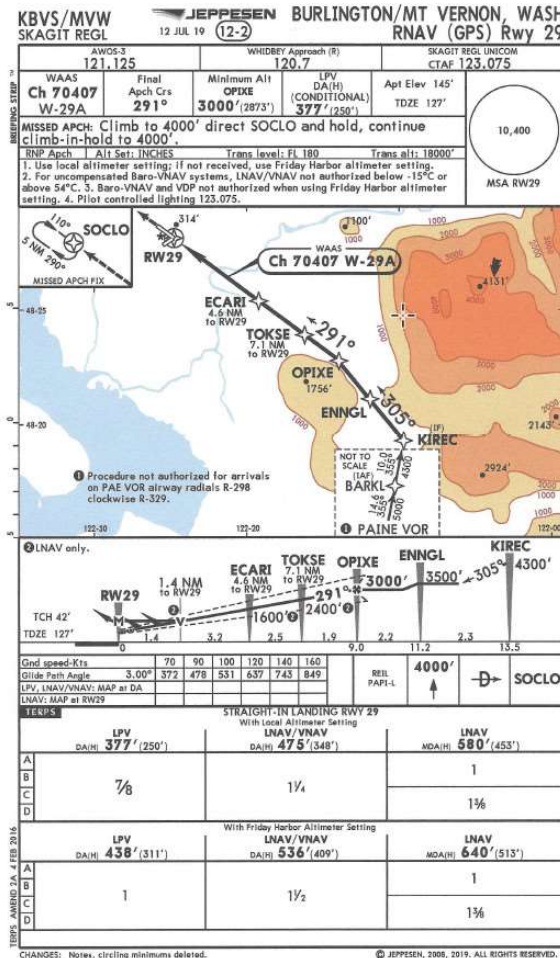


36:22 / 1:03:37 • Abnormal Operations >

Scroll for details



# GFC 500 Autopilot and VNAV



Vertical Modes include:

Altitude Hold

Vertical Speed climb/descend (set by pitch wheel)

Vertical Navigation

Indicated Airspeed climb/descend (set by pitch wheel)

Pitch Hold (default with no other mode)

Settings

IAS      HDG      ALT  
 0 KT    214°    2500 FT

Resources

GARMIN

Com Vol  
 -  
**124.70**  
 KRNT TWR  
 ↓  
 STBY  
 Psh Sq  
**121.60**  
 KRNT GND

Audio Panel  
 Intercom

MIC  
**1**  
 MON  
**1**

XPDR  
 IDENT  
**1200**  
 STBY

NAV SEA  
**116.80**  
 SEA VOR  
 ↓  
 STBY  
 PAE VOR  
**110.60**

PROC - Approach

Sequence

PAE	☐	—°—	— NM
BARKL	▲	355°	14.6 NM
KIREC	▲	355°	10.0 NM
ENGL	▲	306°	2.3 NM
OPIXE	▲	306°	2.2 NM
TOKSE	▲	291°	1.9 NM
ECARI	▲	291°	2.5 NM
RW29	▲	291°	4.6 NM
277 FT		201°	0.5 NM

Airport  
**KBVS**

Approach  
**RNAV 29 GPs LPV**

Transition  
**PAE**

Channel / ID  
**70407 W29A**

Load Approach

Load Approach & Activate

Cancel

Chart

In

Out

ENR    DEMO    GPS

Com Freq / Psh Nav

Track Mode: Manual

-    HDG    +

Push

Settings

IAS      HDG      ALT  
 0 KT    214°    2500 FT

Resources

GARMIN HOME

+  
IAS  
-

+  
ALT  
-

Back

Menu

Up

Down

TERM DEMO GPS
Com Freq / Psh Nav

Track Mode: Manual

-    HDG    +

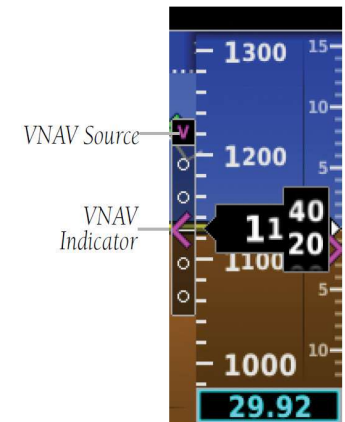


COM	124.70	Audio Panel	MIC	XPDR	116.80
KRNT TWR	↓	Intercom	1	IDENT	SEA VOR
STBY	121.60		MON	1200	STBY
KRNT GND	↓		1	STBY	110.60
				PAE VOR	

Active Flight Plan			
KBVS / KBVS	ALT	DTK	DIS
BARKL <span style="color: cyan;">↑</span> iaf	5000 FT	355°	39.9 NM
KIREC <span style="color: cyan;">↑</span>	4300 FT	355°	10.0 NM
ENNGL <span style="color: cyan;">↑</span>	3500 FT	306°	2.3 NM
OPIXE <span style="color: cyan;">↑</span> faf	3000 FT	306°	2.2 NM
TOKSE <span style="color: cyan;">↑</span>	2400 FT	291°	1.9 NM

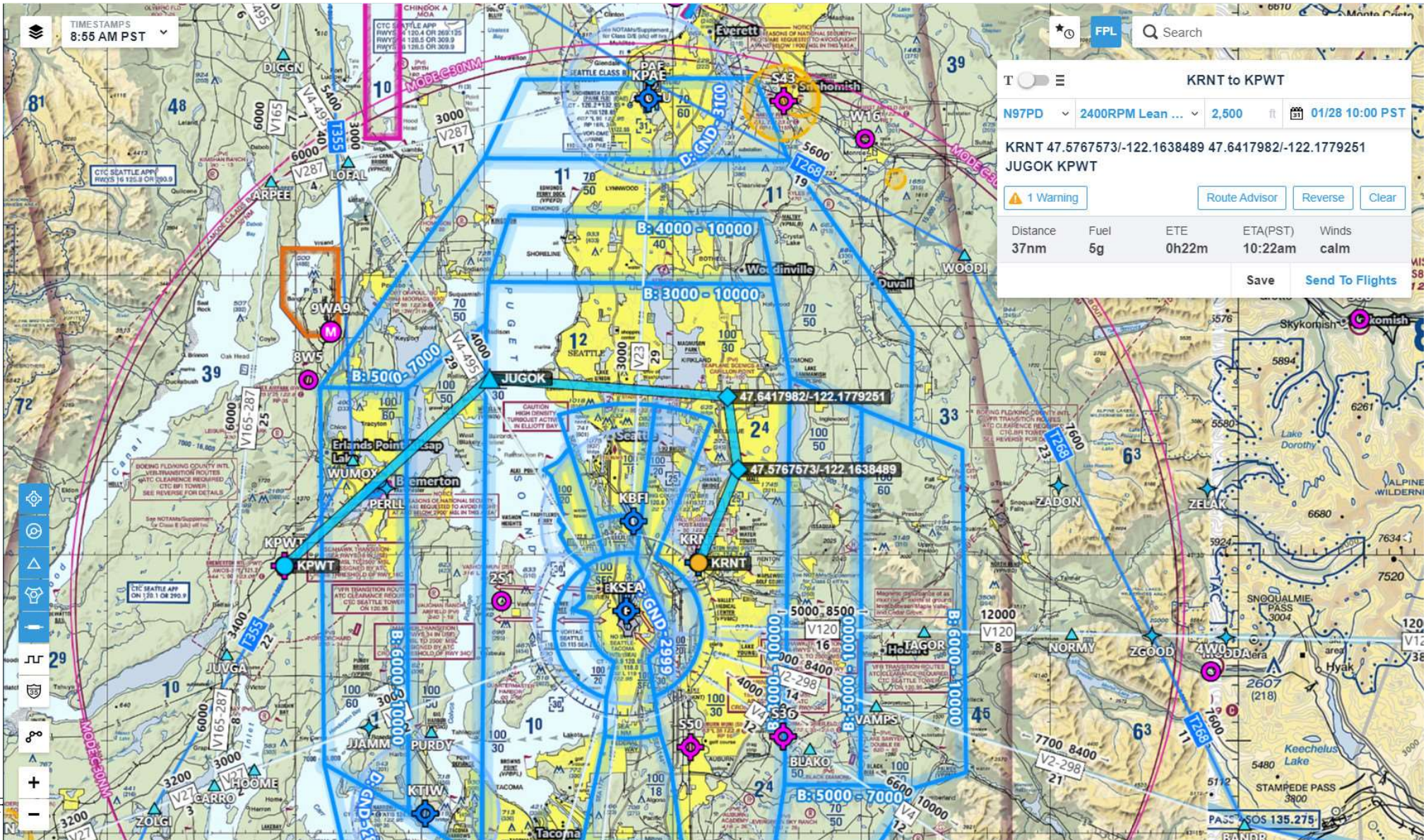
# VNAV Basics

- Have flight plan in the GTN that has valid altitude constraints
- Have active leg in the GTN for navigation
  - GTN calculates and displays TOD and BOD
  - GTN calculates required descent rate for descent path (default 3°)
- Have GTN navigating to valid waypoint and GFC500 in NAV
- Set Altitude Select to authorized descent altitude on G5
- Press VNAV on GFC500 – VPATH should display on G5 as armed (white)
- When 1 minutes from TOD, audio alert “VERTICAL PATH”
- G5 will show a Vertical Deviation Indicator (initially high)
- At TOD, G5 VDI will be at the center, green VPATH, descent commences



Garmin Training Video on VNAV (20 minutes)

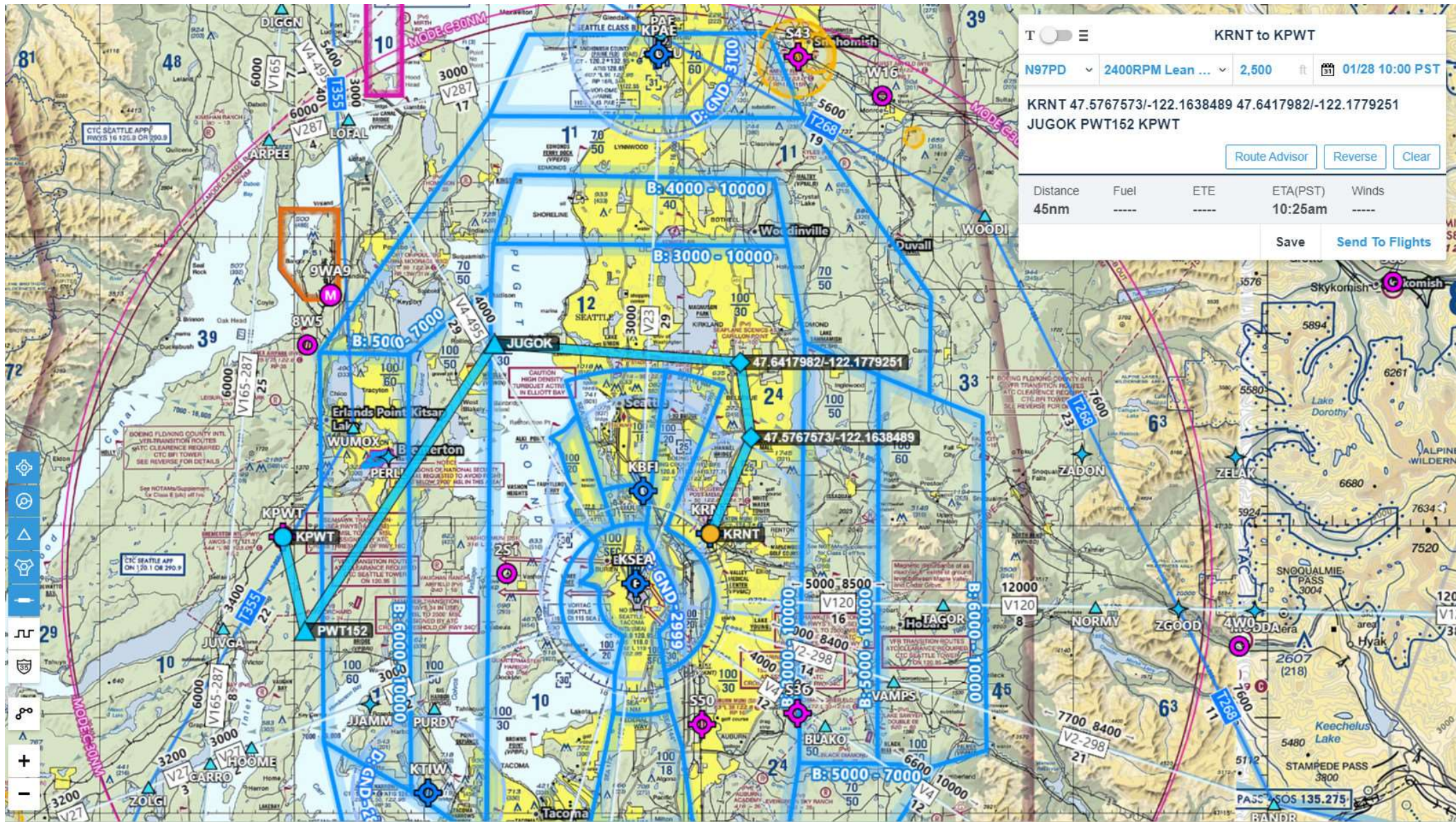
<https://www.youtube.com/watch?v=GxM2k0gOqVU>



GF

20





T   KRNT to KPWT

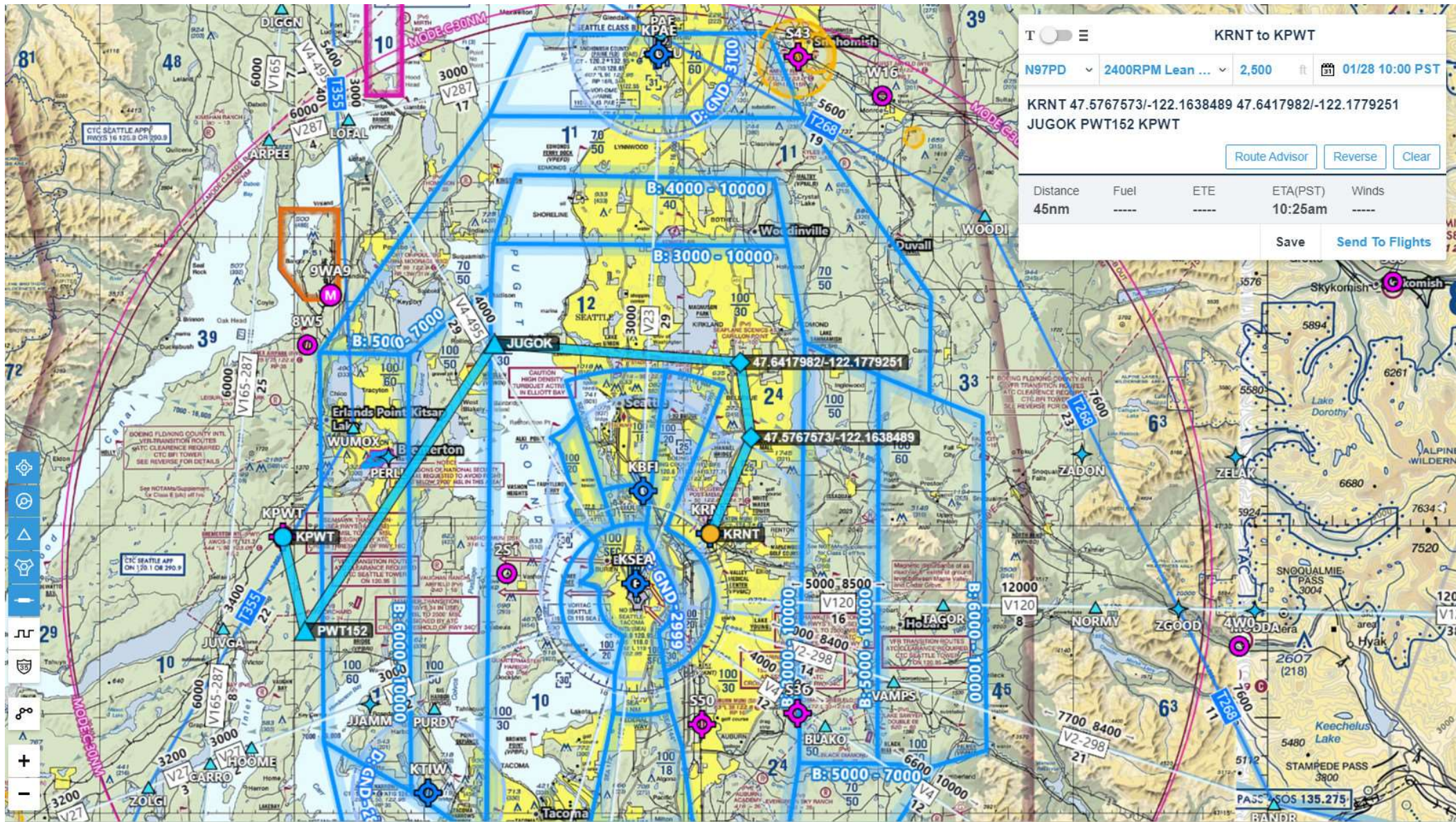
N97PD  2400RPM Lean ...  2,500 ft  01/28 10:00 PST

KRNT 47.5767573/-122.1638489 47.6417982/-122.1779251  
 JUGOK PWT152 KPWT

Distance	Fuel	ETE	ETA(PST)	Winds
45nm	-----	-----	10:25am	-----
			<input type="button" value="Save"/>	<input type="button" value="Send To Flights"/>







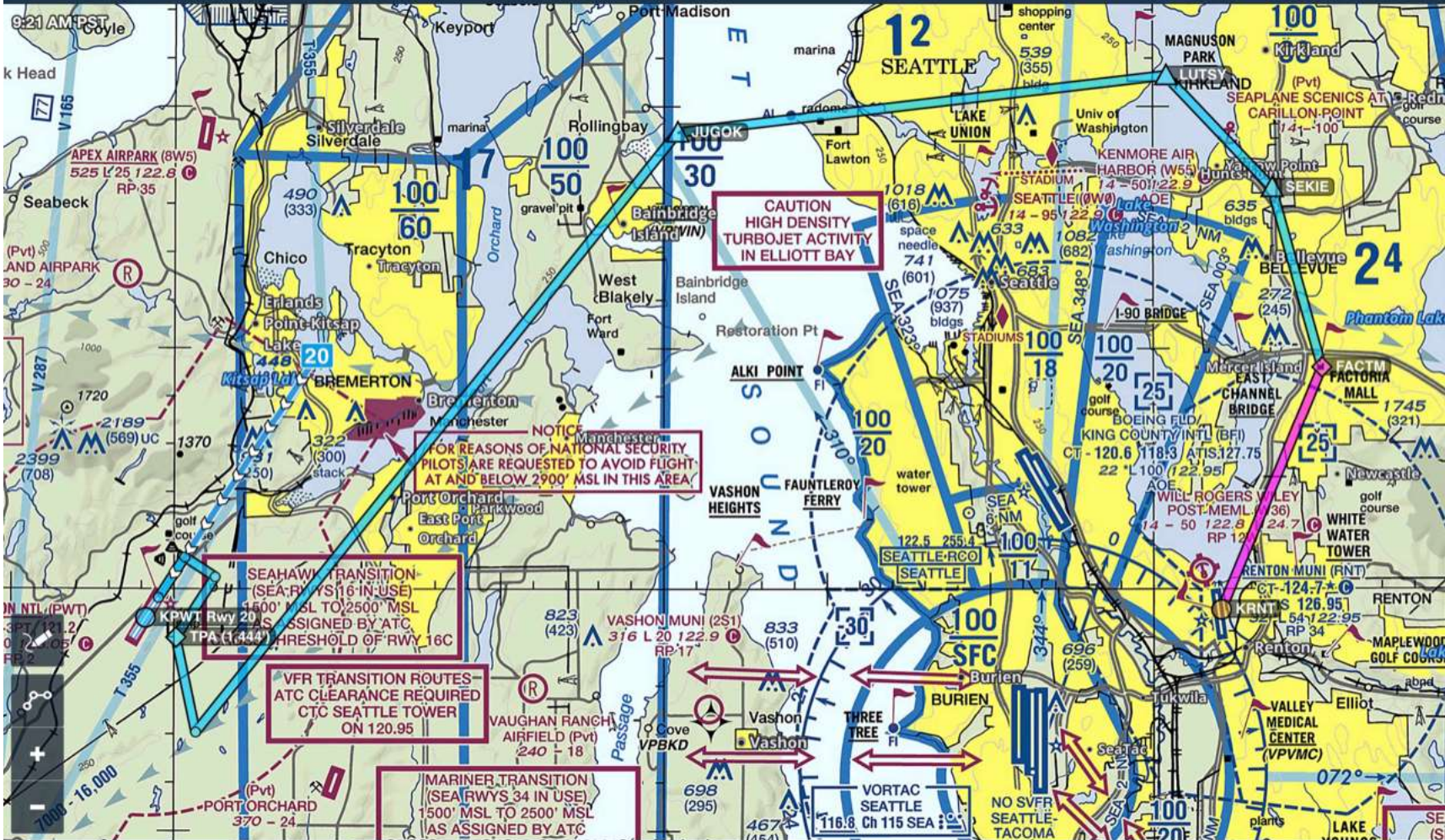
T   KRNT to KPWT

N97PD 2400RPM Lean ... 2,500 ft 01/28 10:00 PST

KRNT 47.5767573/-122.1638489 47.6417982/-122.1779251  
 JUGOK PWT152 KPWT

[Route Advisor](#) [Reverse](#) [Clear](#)

Distance	Fuel	ETE	ETA(PST)	Winds
45nm	----	----	10:25am	----
			<a href="#">Save</a>	<a href="#">Send To Flights</a>



# **GFC 500 Autopilot Coupled Missed Approach/Go-Around**

**Prior to Decision Altitude / Missed Approach Point, set MA Altitude**

- 1. At MAP, Press GA [Wings level roll, and 7° pitch up on AI]**
- 2. Apply Climb Power**
- 3. Verify CDI switched to GPS or Manually Adjust**
- 4. Select HDG / TRK / NAV as Appropriate for the MAP**
- 5. Select IAS for climb**
- 6. Verify Proper Execution of MAP to the typical hold**

# GFC 500 Autopilot

## Two integrated safety systems:

- **When Autopilot is engaged:**
  - **Underspeed Protection (USP)**
  - **Overspeed Protection (OSP)**
- **When Autopilot is NOT engaged:**
  - **Electronic Stability Protection (ESP)**

# GFC 500 Autopilot

## Underspeed Protection (USP) — (autopilot is engaged)

- When the minimum airspeed of 60 KIAS is reached, a visual MINSPD message will appear above the airspeed tape and the autopilot will lower the nose to maintain 60 KIAS.
- An aural “AIRSPEED, AIRSPEED” voice alert will sound for installations connected to an audio panel.
- Underspeed Protection is exited automatically when airspeed exceeds 65 KIAS.



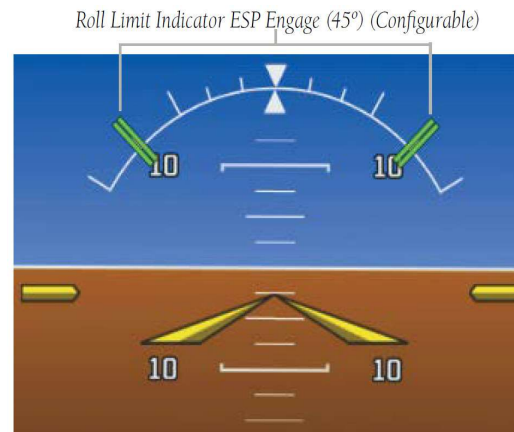
# GFC 500 Autopilot

## **Overspeed Protection (OSP)** — (autopilot is engaged)

- When the maximum airspeed of 150 KIAS is reached, visual MAXSPD message will appear above the airspeed tape and the autopilot will raise the nose of the aircraft to avoid exceeding the maximum configured airspeed.
- An aural “AIRSPEED, AIRSPEED” voice alert will sound for installations connected to an audio panel.



# GFC 500 Electronic Stability Protection



**A separate Electronic Stability Protection (ESP) system monitors aircraft status (Pitch, Bank, Airspeed) when AP is not engaged (inactive at 200' AGL)**

- **ESP will use servo pressure to discourage pilot operations outside of normal operating envelope (pitch +20°, -15°, bank > 45°, airspeed >161kts, <50kts)**
- **ESP will activate the autopilot (with an aural warning) in Level mode if operations are maintained outside the normal operating envelope (Pitch, Bank, Airspeed) for sufficient time – 10 seconds**
- **ESP can be disabled for training via options on the G5, or via holding AP Disconnect**

# GFC 500 Electronic Stability Protection

## Enabling/Disabling ESP using the G5 Menu:

- 1) From the PFD Page, press the Selection Knob to display the Menu.
- 2) Turn the Selection Knob to highlight **ESP**.
- 3) Press the Selection Knob to enable or disable ESP.






Figure 3-25 AFCS (ESP Enabled)

# Other considerations: G5 Battery Status

## 2.1.7 BATTERY STATUS INDICATOR

When the G5 is powered by the aircraft electrical bus, the battery status indicator can be displayed by pressing the G5 Power Button. When the G5 is powered by the battery, the battery status indicator is displayed automatically. This indicator shows the estimated percent charge of the battery. After about one minute on battery power, the indicator shows the estimated time (in hours and minutes) until the battery is empty. The current charge level of the battery is indicated by the filled-in portion of the battery icon. The battery icon turns yellow or red to indicate a low-battery condition

<b>3:15</b> 	<b>41%-100%</b>
<b>1:31</b> 	<b>21%-40%</b>
<b>0:38</b> 	<b>0%-20%</b>

The battery is required for the G5 unit installed as an attitude display indicator (ADI) and is optional for the G5 unit installed as a horizontal situation indicator (HSI)

When the G5 is connected to external power and the battery is being charged, a lightning bolt symbol appears over the battery icon.

<b>92%</b> 	<b>Charging</b>
---	-----------------

# Other considerations: Autopilot on FAA Practical Test

**FAA-S-ACS-6B C1 6-6-2019 Private Pilot Airmen Certification Standards page A-19**

“To assist in management of the aircraft during the practical test, the applicant is expected to demonstrate automation management skills by **utilizing** installed, available, or airborne equipment such as **autopilot**, avionics and systems displays, and/or a flight management system (FMS). The evaluator is expected to test the applicant’s knowledge of the systems that are available or installed and operative during both the ground and flight portions of the practical test.”

# **GFC 500 Autopilot Documentation**

**In addition to the G5 Pilot's Guide, the Autopilot Airplane Flight Manual Supplement (AFMS) for the C172 provides Limitations, Emergency Procedures, Non-Normal Procedures and Normal Procedures for the Autopilot**

**AFMS – GFC 500 Autopilot in Textron 172 Series**  
**[https://static.garmin.com/pumac/190-02291-02\\_08.pdf](https://static.garmin.com/pumac/190-02291-02_08.pdf)**

**G5 Electronic Flight Instrument Pilot's Guide for Certified Aircraft**  
**[https://static.garmin.com/pumac/190-01112-12\\_j.pdf](https://static.garmin.com/pumac/190-01112-12_j.pdf)**

**Extensive (1:03) Sportys / Garmin Webinar Video on GFC 500**  
**<https://www.youtube.com/watch?v=g4YGFbYhoMk>**

# QUESTIONS ???



**Howard Wolvington**

**ATP, Gold Seal CFI-CFII-MEI SEL/SES/MEL**

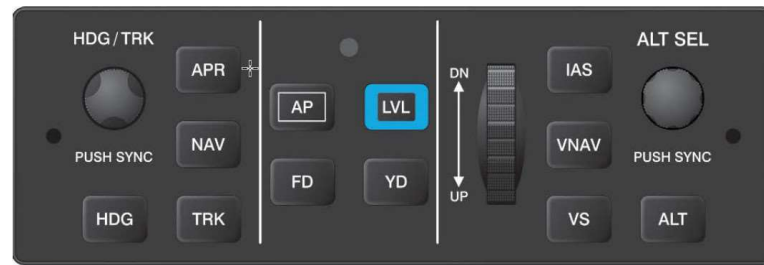
**2014 National CFI of the Year**

**Designated Pilot Examiner**

**Cell Phone: 425-761-4729**

**Email: [Howard@FlyWithHoward.com](mailto:Howard@FlyWithHoward.com)**

# GFC 500 Autopilot



When automatic electric trim is not available:



Figure 3-21 TRIM UP Alert



Figure 3-22 TRIM DOWN Alert